

# Zhile REN

Engineering Manager @ Apple

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## 🎓 EDUCATION

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|-------------|---|
| 2013 – 2018 | <b>Ph.D. in Computer Science @ Brown University</b> <span style="float: right;">Providence, RI</span> <ul style="list-style-type: none"><li>&gt; Thesis : Semantic Three-Dimensional Understanding of Dynamic Scenes</li><li>&gt; Advisor : Prof. Erik Sudderth</li></ul> |
| 2009 – 2013 | <b>B.S in Statistics @ Zhejiang University</b> <span style="float: right;">Hangzhou, China</span>   |

## 📁 WORK EXPERIENCES

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| 2020 – Present      | <b>Engineering Manager @ Apple</b> <span style="float: right;">Seattle, WA</span> <ul style="list-style-type: none"><li>&gt; Current : Hardware-aware efficient-ML frameworks and algorithms. Optimization for large models and Apple Vision Pro/Camera applications</li><li>&gt; Past : 3D vision research and engineering (Depth-API, RoomPlan, research papers)</li><li>&gt; Manager : Dr. Qi Shan</li></ul>  |
| 2018 – 2020         | <b>Postdoctoral Researcher @ Georgia Tech</b> <span style="float: right;">Atlanta, GA</span> <ul style="list-style-type: none"><li>&gt; Embodied AI, 3D scene understanding</li><li>&gt; Supervising and collaborating with PhD students in computer vision projects, papers accepted in ICCV, NeurIPS, AAAI</li><li>&gt; Supervisors : Profs. Dhruv Batra, Devi Parikh, Irfan Essa</li></ul>  |
| 2013 – 2018         | <b>Ph.D. Thesis Research @ Brown University</b> <span style="float: right;">Providence, RI</span> <ul style="list-style-type: none"><li>&gt; 3D object detection and layout prediction on RGB-D images</li><li>&gt; Proposed the Clouds of Oriented Gradients (COG) descriptor for 3D object detection systems, oral presentation at CVPR, and T-PAMI special issue on RGB-D vision</li><li>&gt; Advisor : Prof. Erik Sudderth</li></ul> <b>Ph.D. Research @ Brown University</b> <span style="float: right;">Providence, RI</span> <ul style="list-style-type: none"><li>&gt; Attribute-based image editing algorithms</li><li>&gt; Dataset and algorithm for style transformation, oral presentation at SIGGRAPH</li><li>&gt; Advisor : Prof. James Hays</li></ul> |
| 2016/2017<br>Summer | <b>Research Intern @ NVIDIA Research</b> <span style="float: right;">Santa Clara, CA/Westford, MA</span> <ul style="list-style-type: none"><li>&gt; Semantic scene flow estimation, multi-frame optical flow</li><li>&gt; State-of-the-art algorithms on both KITTI and MPI Sintel at the time of publications, oral presentation at 3DV, and open-source PyTorch code for PWC-Net</li><li>&gt; Supervisors : Drs. Deqing Sun, Orazio Gallo, Jan Kautz, and Prof. Ming-Hsuan Yang</li></ul>  |
| 2015<br>Summer      | <b>Research Intern @ Microsoft Research</b> <span style="float: right;">Redmond, WA</span> <ul style="list-style-type: none"><li>&gt; Image completion and shadow removal algorithms</li><li>&gt; Supervisors : Drs. Sing Bing Kang and Johannes Kopf</li></ul>  |
| 2013<br>Spring      | <b>Research Intern @ National Laboratory of Pattern Recognition</b> <span style="float: right;">Beijing, China</span> <ul style="list-style-type: none"><li>&gt; Agglomerative clustering algorithms for 3D mesh segmentation</li><li>&gt; Supervisor : Prof. Huai-Yu Wu</li></ul>   |
| 2012<br>Summer      | <b>Research Intern @ Toyota Technological Institute at Chicago (TTIC)</b> <span style="float: right;">Chicago, IL</span> <ul style="list-style-type: none"><li>&gt; Agglomerative clustering algorithms for natural image segmentation</li><li>&gt; Spotlight presentation at CVPR</li><li>&gt; Supervisor : Prof. Greg Shakhnarovich</li></ul>  |

## Peer-reviewed Papers

[Google scholar page](#)

- CHI '24 **Talaria : Interactively Optimizing Machine Learning Models for Efficient Inference**  
Fred Hohman, Chaoqun Wang, Jinmook Lee, Jochen Görtler, Dominik Moritz, Jeffrey P. Bigham  
**Zhile Ren**, Cecile Foret, Qi Shan, Xiaoyi Zhang  
ACM Conference on Human Factors in Computing Systems (**CHI 2024**)
- ICML '23 **UPSCALE : Unconstrained Channel Pruning**  
Alvin Wan, Hanxiang Hao, Kaushik Patnaik, Sam Xu, Omer Hadad, David Güera  
**Zhile Ren**, Qi Shan  
International Conference on Machine Learning (**ICML 2023**)
- CVPR '23 **AutoFocusFormer : Image Segmentation off the Grid**  
Chen Ziwen, Kaushik Patnaik, Shuangfei Zhai, Alvin Wan, **Zhile Ren**, Alexander G. Schwing  
Alex Colburn, Li Fuxin  
IEEE Conference on Computer Vision and Pattern Recognition (**CVPR 2023**)
- ECCV '22 **Generative Multiplane Images : Making a 2D GAN 3D-Aware**  
**Oral 3%**  
Xiaoming Zhao, Fangchang Ma, David Güera, **Zhile Ren**, Alexander G. Schwing, Alex Colburn  
European Conference on Computer Vision (**ECCV 2022**)
- CVPR '22 **FvOR : Robust Joint Shape and Pose Optimization for Few-view Object Reconstruction**  
Zhenpei Yang, **Zhile Ren**, Miguel Angel Bautista, Zaiwei Zhang, Qi Shan, Qixing Huang  
IEEE Conference on Computer Vision and Pattern Recognition (**CVPR 2022**)
- CVPR '22 **MVS2D : Efficient Multi-view Stereo via Attention-Driven 2D Convolutions**  
Zhenpei Yang, **Zhile Ren**, Qi Shan, Qixing Huang  
IEEE Conference on Computer Vision and Pattern Recognition (**CVPR 2022**)
- AAAI '21 **Semantic MapNet : Building Allocentric Semantic Maps and Representations from Egocentric Views**  
Vincent Cartillier, **Zhile Ren**, Neha Jain, Stefan Lee, Irfan Essa, Dhruv Batra  
AAAI Conference on Artificial Intelligence (**AAAI 2021**)
- T-PAMI '20 **Clouds of Oriented Gradients for 3D Detection of Objects, Surfaces, and Indoor Scene Layouts**  
**Zhile Ren**, Erik Sudderth  
IEEE Transactions on Pattern Analysis and Machine Intelligence (**T-PAMI 2020**)
- NeurIPS '19 **Cross-Channel Communication Networks**  
Jianwei Yang, **Zhile Ren**, Chuang Gan, Hongyuan Zhu, Devi Parikh  
Neural Information Processing Systems (**NeurIPS 2019**)
- ICCV '19 **Embodied Amodal Recognition : Learning to Move to Perceive Objects**  
Jianwei Yang\*, **Zhile Ren\***, Mingze Xu, Xinlei Chen, David Crandall, Devi Parikh, Dhruv Batra  
(**Equal Contribution\***)  
IEEE International Conference on Computer Vision (**ICCV 2019**)
- ICCV '19 **3D Scene Reconstruction with Multi-layer Depth and Epipolar Transformers**  
Daeyun Shin, **Zhile Ren**, Erik Sudderth, Charless Fowlkes  
IEEE International Conference on Computer Vision (**ICCV 2019**)
- WACV '19 **A Fusion Approach for Multi-Frame Optical Flow Estimation**  
**Zhile Ren**, Orazio Gallo, Deqing Sun, Ming-Hsuan Yang, Jan Kautz, Erik Sudderth  
IEEE Winter Conference on Applications of Computer Vision (**WACV 2019**)
- CVPR '18 **3D Object Detection with Latent Support Surfaces**  
**Zhile Ren**, Erik Sudderth  
IEEE Conference on Computer Vision and Pattern Recognition (**CVPR 2018**)

- 3DV '17 **Cascaded Scene Flow Prediction using Semantic Segmentation**  
 Oral 7% **Zhile Ren**, Deqing Sun, Jan Kautz, Erik Sudderth  
 International Conference on 3D Vision (**3DV 2017**)
- CVPR '16 **3D Object Detection and Layout Prediction using Clouds of Oriented Gradients**  
 Oral 3% **Zhile Ren**, Erik Sudderth  
 IEEE Conference on Computer Vision and Pattern Recognition (**CVPR 2016**)
- IROS '15 **Robust Graph SLAM in Dynamic Environments with Moving Landmarks**  
 Lingzhu Xiang, **Zhile Ren**, Mengrui Ni, Chad Jenkins  
 International Conference on Intelligent Robots and Systems (**IROS 2015**)
- SIGGRAPH 14' **Transient Attributes for High-Level Understanding and Editing of Outdoor Scenes**  
 Pierre-Yves Laffont, **Zhile Ren**, Xiaofeng Tao, Chao Qian, James Hays  
 ACM Transactions on Graphics (**SIGGRAPH 2014**)
- CVPR '13 **Image Segmentation by Cascaded Region Agglomeration**  
**Zhile Ren**, Greg Shakhnarovich  
 IEEE Conference on Computer Vision and Pattern Recognition (**CVPR 2013**)
- Workshop Papers**
- CVPR-W '19 **Multi-layer Depth and Epipolar Feature Transformers for 3D Scene Reconstruction**  
 Oral Daeyun Shin, **Zhile Ren**, Erik Sudderth, Charless Fowlkes  
 SUMO : 360° Indoor Scene Understanding and Modeling (**CVPR Workshop 2019**)
- ECCV-W '18 **A Simple and Effective Fusion Approach for Multi-frame Optical Flow Estimation**  
**Zhile Ren**, Orazio Gallo, Deqing Sun, Ming-Hsuan Yang, Jan Kautz, Erik Sudderth  
 ECCV Workshop : What is optical flow for? (**ECCV Workshop 2018**)

## ACADEMIC SERVICES

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Reviewer

### Meta Reviewer

- > AAI Conference on Artificial Intelligence (**AAAI**) 2022

### Journal Reviewer

- > IEEE Transactions on Pattern Analysis and Machine Intelligence (**T-PAMI**)
- > ACM Transactions on Graphics (**TOG**)
- > Journal of Machine Learning Research (**JMLR**)
- > Computer Vision and Image Understanding (**CVIU**)
- > IEEE Transactions on Image Processing (**TIP**)
- > IEEE Robotics and Automation Letters (**RA-L**)
- > Robotics and Autonomous Systems (**RAS**)
- > Transactions on Machine Learning Research (**TMLR**)
- > Journal of Machine Learning Research (**JMLR**)

### Conference Reviewer

- > IEEE International Conference on Computer Vision (**ICCV**)
- > IEEE Conference on Computer Vision and Pattern Recognition (**CVPR**)
- > European Conference on Computer Vision (**ECCV**)
- > British Machine Vision Conference (**BMVC**)
- > Asian Conference on Computer Vision (**ACCV**)
- > IEEE Winter Conference on Applications of Computer Vision (**WACV**)
- > International Conference on Learning Representations (**ICLR**)
- > AAI Conference on Artificial Intelligence (**AAAI**)
- > Neural Information Processing Systems (**NeurIPS**)
- > International Conference on Machine Learning (**ICML**)

### Outstanding Reviewer Awards

- > IEEE Conference on Computer Vision and Pattern Recognition (**CVPR**) 2021
- > AAI Conference on Artificial Intelligence (**AAAI**) 2021

## INVITED TALKS

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- 2019 | **Amodal Perception in 3D Environments**
  - > Seminar in **Horizon Robotics, Nuro, Vicarious, Apple, Google Research, Amazon Robotics, Uber ATG, Cruise, Samsung Research, Niantic Labs**
- 2018 | **Semantic Three-Dimensional Understanding of Dynamic Scenes**
  - > Seminar in **Amazon, Microsoft, UC San Diego, MIT, UC Irvine, Georgia Tech**
- 2017 | **Cascaded Scene Flow Prediction using Semantic Segmentation**
  - > International Conference on 3D Vision (**3DV**); New England Computer Vision Workshop; Seminar at **NVIDIA, UC Irvine, Boston University**
- 2016 | **3D Object Detection and Layout Prediction using Clouds of Oriented Gradients**
  - > IEEE Conference on Computer Vision and Pattern Recognition (**CVPR**); New England Computer Vision Workshop; Guest lecture at **Brown University**; Seminar at **NVIDIA**
- 2012 | **Image Segmentation by Cascaded Region Agglomeration**
  - > Midwest Vision Workshop



## TEACHING EXPERIENCES

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- Lecture | **Guest Lecturer**
  - > CS 4476 : Intro to Computer Vision, **Georgia Tech**, Summer 2019
  - > CS 4803/7643 : Deep Learning, **Georgia Tech**, Fall/Spring 2018/2019
- Teaching Assistant | **Teaching Assistant**
  - > CSCI2420 : Probabilistic Graphical Models, **Brown University**, Fall 2016
  - > CSCI1450 : Introduction to Probability & Computing, **Brown University**, Spring 2015



## MEDIA COVERAGES

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### Transient Attributes for High-Level Understanding and Editing of Outdoor Scenes, SIGGAPH '14

- IEEE Spectrum | [Transform Your Photos with a Magic Word](#)
- NBC News | [Don't Like the Weather in Your Photos? Now You Can Change It](#)
- PBS | [Scientists launch technology that can change the weather...in your photos](#)
- MIC | [These Vivid Photo Filters of the Future Make Instagram Look Like Child's Play](#)
- Gizmodo | [This Algorithm Can Change the Season and Weather In Your Photos](#)
- Brown News | [Photo editing algorithm changes weather, seasons automatically](#)

### Semantic MapNet : Building Allocentric Semantic Maps and Representations from Egocentric Views, AAAI '21

- Venturebeat | [Facebook releases tools to help AI navigate complex environments](#)
- ZDNet | [Facebook is building home robots to help you find your ringing phone](#)
- MIT-TR | [Facebook is training robot assistants to hear as well as see](#)
- Digital Trends | [Facebook's new 'embodied A.I.' project aims to build a new breed of robots](#)