7hile **Rfn**

Engineering Manager @ Apple

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EDUCATION —

2013 – 2018 | Ph.D. in Computer Science @ Brown University

Providence, RI

> Thesis: Semantic Three-Dimensional Understanding of Dynamic Scenes

> Advisor: Prof. Erik Sudderth

2009 – 2013 | B.S in Statistics @ Zhejiang University

Hangzhou, China



WORK EXPERIENCES —

2020 – Present | **Engineering Manager @ Apple**

Seattle, WA

> Current: Hardware-aware efficient-ML frameworks and algorithms. Optimization for large models and Apple Vision Pro/Camera applications

> Past: 3D vision research and engineering (Depth-API, RoomPlan, research papers)

> Manager : Dr. Qi Shan

2018 - 2020

Postdoctoral Researcher @ Georgia Tech

Atlanta, GA

> Embodied AI, 3D scene understanding

> Supervising and collaborating with PhD students in computer vision projects, papers accepted in ICCV, NeurIPS, AAAI

> Supervisors: Profs. Dhruv Batra, Devi Parikh, Irfan Essa

2013 – 2018 | Ph.D. Thesis Research @ Brown University

Providence, RI

> 3D object detection and layout prediction on RGB-D images

> Proposed the Clouds of Oriented Gradients (COG) descriptor for 3D object detection systems, oral presentation at CVPR, and T-PAMI special issue on RGB-D vision

> Advisor: Prof. Erik Sudderth

Ph.D. Research @ Brown University

Providence, RI

> Attribute-based image editing algorithms

> Dataset and algorithm for style transformation, oral presentation at SIGGRAPH

> Advisor: Prof. James Hays

2016/2017 | Research Intern @ NVIDIA Research

Santa Clara, CA/Westford, MA

Summer

> Semantic scene flow estimation, multi-frame optical flow

> State-of-the-art algorithms on both KITTI and MPI Sintel at the time of publications, oral presentation at 3DV, and open-source PyTorch code for PWC-Net

> Supervisors: Drs. Deging Sun, Orazio Gallo, Jan Kautz, and Prof. Ming-Hsuan Yang

2015

Research Intern @ Microsoft Research

Redmond, WA

Summer

> Image completion and shadow removal algorithms

> Supervisors : Drs. Sing Bing Kang and Johannes Kopf

2013 Spring

Research Intern @ National Laboratory of Pattern Recognition > Agglomerative clustering algorithms for 3D mesh segmentation

Beijing, China

> Supervisor: Prof. Huai-Yu Wu

2012 Summer

Research Intern @ Toyota Technological Institute at Chicago (TTIC) > Agglomerative clustering algorithms for natural image segmentation

Chicago, IL

> Spotlight presentation at CVPR

> Supervisor: Prof. Greg Shakhnarovich



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Google scholar page

CHI '24	Talaria: Interactivel	y Optimizing	Machine Learning	Models for Et	fficient Inference

Tred Hohman, Chaoqun Wang, Jinmook Lee, Jochen Görtler, Dominik Moritz, Jeffrey P. Bigham Zhile Ren, Cecile Foret, Qi Shan, Xiaoyi Zhang

ACM Conference on Human Factors in Computing Systems (CHI 2024, Honorable Mention)

ICML '23 UPSCALE: Unconstrained Channel Pruning

Alvin Wan, Hanxiang Hao, Kaushik Patnaik, Sam Xu, Omer Hadad, David Güera **Zhile Ren**, Qi Shan International Conference on Machine Learning (ICML 2023)

CVPR '23 AutoFocusFormer: Image Segmentation off the Grid

Chen Ziwen, Kaushik Patnaik, Shuangfei Zhai, Alvin Wan, **Zhile Ren**, Alexander G. Schwing Alex Colburn, Li Fuxin IEEE Conference on Computer Vision and Pattern Recognition (CVPR 2023)

ECCV '22 Generative Multiplane Images: Making a 2D GAN 3D-Aware

Oral 3% Xiaoming Zhao, Fangchang Ma, David Güera, **Zhile Ren**, Alexander G. Schwing, Alex Colburn European Conference on Computer Vision (ECCV 2022)

CVPR '22 **FvOR: Robust Joint Shape and Pose Optimization for Few-view Object Reconstruction**Zhenpei Yang, **Zhile Ren**, Miguel Angel Bautista, Zaiwei Zhang, Qi Shan, Qixing Huang
IEEE Conference on Computer Vision and Pattern Recognition **(CVPR 2022)**

CVPR '22 MVS2D: Efficient Multi-view Stereo via Attention-Driven 2D Convolutions
Zhenpei Yang, Zhile Ren, Qi Shan, Qixing Huang
IEEE Conference on Computer Vision and Pattern Recognition (CVPR 2022)

AAAI '21 Semantic MapNet: Building Allocentric Semantic Maps and Representations from Egocentric Views

Vincent Cartillier, **Zhile Ren**, Neha Jain, Stefan Lee, Irfan Essa, Dhruv Batra AAAI Conference on Artificial Intelligence (AAAI 2021)

T-PAMI '20 Clouds of Oriented Gradients for 3D Detection of Objects, Surfaces, and Indoor Scene Layouts Zhile Ren, Erik Sudderth

IEEE Transactions on Pattern Analysis and Machine Intelligence (T-PAMI 2020)

NeurlPS '19 Cross-Channel Communication Networks

Jianwei Yang, **Zhile Ren**, Chuang Gan, Hongyuan Zhu, Devi Parikh Neural Information Processing Systems (**NeurIPS 2019**)

ICCV '19 Embodied Amodal Recognition : Learning to Move to Perceive Objects

Jianwei Yang*, **Zhile Ren***, Mingze Xu, Xinlei Chen, David Crandall, Devi Parikh, Dhruv Batra (**Equal Contribution***)

IEEE International Conference on Computer Vision (ICCV 2019)

ICCV '19 3D Scene Reconstruction with Multi-layer Depth and Epipolar Transformers

Daeyun Shin, **Zhile Ren**, Erik Sudderth, Charless Fowlkes IEEE International Conference on Computer Vision (ICCV 2019)

WACV '19 A Fusion Approach for Multi-Frame Optical Flow Estimation

Zhile Ren, Orazio Gallo, Deqing Sun, Ming-Hsuan Yang, Jan Kautz, Erik Sudderth IEEE Winter Conference on Applications of Computer Vision (**WACV 2019**)

CVPR '18 3D Object Detection with Latent Support Surfaces

Zhile Ren, Erik Sudderth

IEEE Conference on Computer Vision and Pattern Recognition (CVPR 2018)

3DV '17 Cascaded Scene Flow Prediction using Semantic Segmentation Oral 7% Zhile Ren, Deging Sun, Jan Kautz, Erik Sudderth

International Conference on 3D Vision (3DV 2017)

CVPR '16 3D Object Detection and Layout Prediction using Clouds of Oriented Gradients

Oral 3% Zhile Ren, Erik Sudderth

IEEE Conference on Computer Vision and Pattern Recognition (CVPR 2016)

Robust Graph SLAM in Dynamic Environments with Moving Landmarks IROS '15

Lingzhu Xiang, Zhile Ren, Mengrui Ni, Chad Jenkins

International Conference on Intelligent Robots and Systems (IROS 2015)

Transient Attributes for High-Level Understanding and Editing of Outdoor Scenes SIGGRAPH

14' Pierre-Yves Laffont, **Zhile Ren**, Xiaofeng Tao, Chao Qian, James Hays ACM Transactions on Graphics (SIGGRAPH 2014)

CVPR'13 Image Segmentation by Cascaded Region Agglomeration

Zhile Ren, Greg Shakhnarovich

IEEE Conference on Computer Vision and Pattern Recognition (CVPR 2013)

Workshop Papers

CVPR-W '19 Multi-layer Depth and Epipolar Feature Transformers for 3D Scene Reconstruction

Oral Daeyun Shin, Zhile Ren, Erik Sudderth, Charless Fowlkes SUMO: 360° Indoor Scene Understanding and Modeling (CVPR Workshop 2019)

ECCV-W'18 A Simple and Effective Fusion Approach for Multi-frame Optical Flow Estimation

Zhile Ren, Orazio Gallo, Deqing Sun, Ming-Hsuan Yang, Jan Kautz, Erik Sudderth

ECCV Workshop: What is optical flow for? (ECCV Workshop 2018)



Reviewer | Meta Reviewer

> AAAI Conference on Artificial Intelligence (AAAI) 2022

Journal Reviewer

- > IEEE Transactions on Pattern Analysis and Machine Intelligence (T-PAMI)
- > ACM Transactions on Graphics (TOG)
- > Journal of Machine Learning Research (JMLR)
- > Computer Vision and Image Understanding (CVIU)
- > IEEE Transactions on Image Processing (TIP)
- > IEEE Robotics and Automation Letters (RA-L)
- > Robotics and Autonomous Systems (RAS)
- > Transactions on Machine Learning Research (TMLR)
- > Journal of Machine Learning Research (JMLR)

Conference Reviewer

- > IEEE International Conference on Computer Vision (ICCV)
- > IEEE Conference on Computer Vision and Pattern Recognition (CVPR)
- > European Conference on Computer Vision (ECCV)
- > British Machine Vision Conference (BMVC)
- > Asian Conference on Computer Vision (ACCV)
- > IEEE Winter Conference on Applications of Computer Vision (WACV)
- > International Conference on Learning Representations (ICLR)
- > AAAI Conference on Artificial Intelligence (AAAI)
- > Neural Information Processing Systems (NeurIPS)
- > International Conference on Machine Learning (ICML)

Outstanding Reviewer Awards

- > IEEE Conference on Computer Vision and Pattern Recognition (CVPR) 2021
- > AAAI Conference on Artificial Intelligence (AAAI) 2021



MINVITED TALKS

Amodal Perception in 3D Environments 2019

> Seminar in Horizon Robotics, Nuro, Vicarious, Apple, Google Research, Amazon Robotics, Uber ATG, Cruise, Samsung Research, Niantic Labs

Semantic Three-Dimensional Understanding of Dynamic Scenes

> Seminar in Amazon, Microsoft, UC San Diego, MIT, UC Irvine, Georgia Tech

Cascaded Scene Flow Prediction using Semantic Segmentation 2017

> International Conference on 3D Vision (3DV); New England Computer Vision Workshop; Seminar at NVIDIA, UC Irvine, Boston University

3D Object Detection and Layout Prediction using Clouds of Oriented Gradients

> IEEE Conference on Computer Vision and Pattern Recognition (CVPR); New England Computer Vision Workshop; Guest lecture at **Brown University**; Seminar at **NVIDIA**

Image Segmentation by Cascaded Region Agglomeration

> Midwest Vision Workshop

TEACHING EXPERIENCES

Lecture | Guest Lecturer

> CS 4476: Intro to Computer Vision, Georgia Tech, Summer 2019 > CS 4803/7643 : Deep Learning, Georgia Tech, Fall/Spring 2018/2019

Teaching | **Teaching Assistant**

Assistant

> CSCI2420: Probablistic Graphical Models, Brown University, Fall 2016

> CSCI1450: Introduction to Probability & Computing, Brown University, Spring 2015

■ Media Coverages -

Transient Attributes for High-Level Understanding and Editing of Outdoor Scenes, SIGGAPH '14

Transform Your Photos with a Magic Word **IEEE Spectrum**

NBC News Don't Like the Weather in Your Photos? Now You Can Change It

PBS Scientists launch technology that can change the weather...in your photos These Vivid Photo Filters of the Future Make Instagram Look Like Child's Play MIC

This Algorithm Can Change the Season and Weather In Your Photos Gizmodo Brown News Photo editing algorithm changes weather, seasons automatically

Semantic MapNet: Building Allocentric Semantic Maps and Representations from Egocentric Views, AAAI '21

Venturebeat Facebook releases tools to help AI navigate complex environments ZDNet Facebook is building home robots to help you find your ringing phone

Facebook is training robot assistants to hear as well as see MIT-TR

Facebook's new 'embodied A.I' project aims to build a new breed of robots Digital Trends